Invariance Principle for Variable Speed Random Walks on Trees

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Variable speed BMs and RWs on ${\mathbb R}$

Object Donsker: $\hat{X} = (\hat{X}_t)_{t \ge 0}$ (cont. time) RW on \mathbb{Z} , $X_t^n := \frac{1}{n} \hat{X}_{n^2 t}$

• X_t^n is RW on $\frac{1}{n}\mathbb{Z}$ with (homogeneous) jump rates $n^2 = n \cdot n$

 $\rightsquigarrow X^n \xrightarrow{\mathcal{L}} X$ in Skorohod pathspace, where X is Brownian motion

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 $\mathrm{d}X_t = \sigma(X_t)\,\mathrm{d}B_t$

- "variable speed", speed measure ν = 1/σ² · λ_R
 → We call X the ν-Brownian motion (ν-BM)
- Need variable rates for RWs X^n on $\frac{1}{n}\mathbb{Z}$ to obtain $X^n \xrightarrow{\mathcal{L}} X$.

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- Need variable rates for RWs X^n on $\frac{1}{n}\mathbb{Z}$ to obtain $X^n \xrightarrow{\mathcal{L}} X$.
- For measure ν_n on $\frac{1}{n}\mathbb{Z}$, let X^n jump from x at rate $\frac{n}{\nu_n(\{x\})}$ \sim We call X^n the ν_n -random walk (ν_n -RW)
- Example: $\nu = \lambda_{\mathbb{R}}, \ \nu_n = n \cdot \# \rightsquigarrow$ situation of Observe: $\nu_n \to \nu$ vaguely.

Speed-u motions on ${\mathbb R}$

 ν -BM: $\nu = \sigma^{-2}\lambda_{\mathbb{R}}$ solves $dX_t = \sigma(X_t)dB_t$; ν -RW: jump rates $\frac{n}{\nu(\{x\})}$ on $\frac{1}{n}\mathbb{Z}$

What do ν -BMs and ν -RWs have in common?

- process on supp(ν), does not jump over points in supp(ν)
- natural scale, i.e. $\mathbb{P}_x(\{\tau_a < \tau_b\}) = \frac{b-x}{b-a}$ if $x \in [a, b]$
- speed determined by $\nu \, \rightsquigarrow \,$ process characterised by ν

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- time transformation of BM: Let $L_s(x)$ be local time of B at x

$$X_t = B_{s_t}, \qquad s_t = \inf\left\{s \mid \int L_s \,\mathrm{d}\nu > t\right\} \tag{1}$$

• Alternative: characterise via occupation time formula (x > a)

$$\mathbb{E}_{\mathsf{x}}\left(\int_{0}^{\tau_{\mathsf{a}}} f(X_{t}) \, \mathrm{d}t\right) = \frac{1}{2} \int_{\mathsf{a}}^{\infty} f(y) \left(|y-\mathsf{a}| \wedge |x-\mathsf{a}|\right) \nu(\mathrm{d}y) \quad (2)$$

 \rightsquigarrow For any *Radon measure* ν on \mathbb{R} , the **speed**- ν **motion** X on $supp(\nu)$ is defined by (1), or (2) + strong Markov property

Stone's invariance principle & Our goal

2 SDE
$$dX_t = \sigma(X_t) dB_t$$
, $\nu = \sigma^{-2} \lambda_{\mathbb{R}}$; ν_n -RW: rates $\frac{n}{\nu_n(\{x\})}$ on $\frac{1}{n}\mathbb{Z}$

Theorem ([STONE '63], continuity in ν of speed- ν motions)

 $\nu_n \to \nu$ vaguely, $\operatorname{supp}(\nu_n) \to \operatorname{supp}(\nu)$ in local Hausdorff topology. Then $X^n \xrightarrow{\mathcal{L}} X$ in pathspace. (X^n speed- ν_n motion, X speed- ν motion)

Example: can approximate SDE of **2** by RWs on $\frac{1}{n}\mathbb{Z}$ with rates

$$n \cdot \nu \left([x, x + \frac{1}{n}] \right)^{-1} = n \left(\int_{x}^{x + \frac{1}{n}} \frac{1}{\sigma^{2}(y)} \, \mathrm{d}y \right)^{-1}$$

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Goal

Generalise Stone's theorem to converging trees $\mathcal{T}_n o \mathcal{T}$ replacing \mathbbm{R}

Example: RW on Galton-Watson tree (conditioned on size *n*) $\xrightarrow{\mathcal{L}}$ BM on Aldous's *Brownian Continuum Random Tree (CRT)* This particular case shown in [CROYDON '08: Convergence of simple...] Stone's invariance principle & Our goal

2 SDE
$$dX_t = \sigma(X_t) dB_t$$
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Theorem ([STONE '63], continuity in ν of speed- ν motions)

 $\nu_n \to \nu$ vaguely, $\operatorname{supp}(\nu_n) \to \operatorname{supp}(\nu)$ in local Hausdorff topology. Then $X^n \xrightarrow{\mathcal{L}} X$ in pathspace. (X^n speed- ν_n motion, X speed- ν motion)

Goal

Generalise Stone's theorem to converging trees $T_n \rightarrow T$ replacing $\mathbb R$

Result (informal): *continuity* of $(T, \nu) \mapsto X$ for the speed- ν motion X on T **ToDo** for precise formulation:

- **O** Define what we mean by *tree*: metric measure tree (T, ν)
- 2 Define *v*-motions on metric measure trees
- Define convergence of metric measure trees and of processes living on different spaces T_n, T

A metric space (T, r) is 0-hyperbolic if the 4-point condition holds:

$$r(x_1, x_2) + r(x_3, x_4) \le \max \{r(x_1, x_3) + r(x_2, x_4), r(x_1, x_4) + r(x_2, x_3)\}$$

0-hyperbolicity implies for $x, y, z \in T$:

• $[x, y] := \{ m \in T \mid r(x, y) = r(x, m) + r(m, y) \} \subseteq T$ is isometric to a subset of the interval $[0, r(x, y)] \subseteq \mathbb{R}$,

•
$$\#([x,y]\cap [y,z]\cap [z,x]) \leq 1$$

• If (T, r) is connected, it is an \mathbb{R} -tree

Note: \mathbb{R} -trees (usually) have curvature $-\infty \rightarrow no$ *CD-condition* (*T*, *r*) is **Heine-Borel** if *closed*, *bounded sets are compact*. A measure ν is **boundedly-finite** if $\nu(A) < \infty$ for *bounded* $A \subseteq T$

Definition (Metric measure tree)

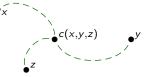
A (rooted) metric measure tree (mm-tree) is (T, r, ρ, ν) , where

• (T, r) is a 0-hyperbolic Heine-Borel space with

$$[x,y] \cap [y,z] \cap [z,x] = c(x,y,z) \in T$$

- $\rho \in T$, called the **root**
- ν is a *boundedly-finite* measure on T with full support, supp(ν) = T

c(x, y, z) is the branch point corresponding to x, y, z

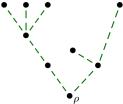


From now on, $x = (T, r, \rho, \nu)$, $x_n = (T_n, r_n, \rho_n, \nu_n)$ are mm-trees

Particular cases of metric trees

An edge in (T, r) is a pair (x, y), $x \neq y \in T$, with $[x, y] = \{x, y\}$ finite trees

- (T, E) finite (undirected) graph tree with edge weights $r_{x,y} > 0$, $(x, y) \in E$
- Metric r on T: maximal extension of $r(x, y) := r_{x,y}, (x, y) \in E$
- \rightsquigarrow (*T*, *r*) topologically discrete, 0-hyperbolic
- \rightsquigarrow edges are precisely the elements of E

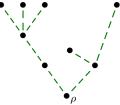


finite tree: edges (dashed) are not in the space (T, r)

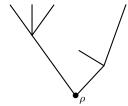
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- Metric r on T: maximal extension of $r(x, y) := r_{x,y}, (x, y) \in E$
- \rightarrow (*T*, *r*) topologically discrete, 0-hyperbolic \rightarrow *edges* are precisely the elements of *E*
- \mathbb{R} -trees
 - Connected 0-hyperbolic ~> no edges
 - infinite degrees, dense leaves possible
 - Hausdorff dimension arbitrary, topological dimension one → fractal



finite tree: edges (dashed) are not in the space (T, r)



corresponding \mathbb{R} -tree: no edges

Speed- ν motions on trees

 $x = (T, r, \rho, \nu)$ is an mm-tree. Recall $T = \text{supp}(\nu)$, c(x, y, z) is branch point

Proposition ([Athreya, L., WINTER '14⁺: *Invariance...*], compact case)

If (T, r) is compact, then there exists a unique strong Markov process $X = (X_t)_{t \ge 0}$ on T satisfying the occupation time formula

$$\mathbb{E}_{\mathsf{x}}\left[\int_{0}^{\tau_{\mathsf{y}}} f(\mathsf{X}_{\mathsf{s}}) \, \mathrm{d}\mathsf{s}\right] = 2 \int_{\mathcal{T}} r(\mathsf{y}, \mathsf{c}(\mathsf{x}, \mathsf{y}, \mathsf{z})) f(\mathsf{z}) \, \nu(\mathrm{d}\mathsf{z})$$

for all $x, y \in T$, f bounded measurable, τ_y first hitting time of y. ν is reversible for X. We call X the speed- ν motion on (T, r).

Proofidea.

Uniqueness: Resolvent calculation **Existence:** Construct via *Dirichlet form* (see following slides)

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for all $x, y \in T$, f bounded measurable, τ_y first hitting time of y. ν is reversible for X. We call X the speed- ν motion on (T, r).

Remark (general case)

- If (T, r) is not compact, we still get a unique strong Markov process X, also called speed-ν motion, by approximating with balls B_R(ρ) (R→∞). Or using the Dirichlet form
- If X is recurrent, we still obtain the occupation time formula

The Dirichlet form

Unsurprisingly, the *Dirichlet form* of the speed- ν motion in defined on $L^2(\nu)$ as the closure of $(\mathcal{E}, \mathcal{D}(\mathcal{E}))$ with

$$egin{aligned} \mathcal{E}(f,g) &= rac{1}{2} \int_{\mathcal{T}}
abla f \cdot
abla g \, \mathrm{d}\lambda_{\mathcal{T}}, \qquad f,g \in \mathcal{D}(\mathcal{E}), \ \mathcal{D}(\mathcal{E}) &= ig\{ f \in L^2(
u) \cap \mathcal{C}_\infty \mid
abla f \in L^2(\lambda_{\mathcal{T}}) ig\}, \end{aligned}$$

but we have to define the *length measure* λ_T and the *gradient* ∇ properly.

The Dirichlet form: Length measure on metric trees

$$\mathcal{E}(f,g) = \frac{1}{2} \int_{\mathcal{T}} \nabla f \cdot \nabla g \, \mathrm{d} \lambda_{\mathcal{T}}, \ \mathcal{D}(\mathcal{E}) = \{ f \in L^2(\nu) \cap \mathcal{C}_{\infty} \mid \nabla f \in L^2(\lambda_{\mathcal{T}}) \}$$

Lemma (length measure λ_T)

There is a unique measure $\lambda_T = \lambda_{(T,r,\rho)}$ (length measure) with

$$\lambda_T([\rho, x]) = r(\rho, x) \ \forall x \in T \quad and \quad \lambda_T(L) = 0,$$

where L consists of ρ and all leaves that are not isolated in (T, r).

- For $T = \mathbb{R}$, $\lambda_{\mathbb{R}}$ is the Lebesgue-measure
- λ_T need not be locally finite, but is always σ -finite
- For **ℝ-trees** (i.e. (*T*, *r*) connected), λ_T is the usual length measure (1-dim. Hausdorff measure on T \ L)
 → non-atomic and independent of ρ

 If (T, r) has an edge, λ_T has an *atom* at the end further away from ρ. Its mass equals the length of the edge.

In particular, λ_T depends in this case on ρ

The Dirichlet form: Gradient on metric trees

$$\mathcal{E}(f,g) = \frac{1}{2} \int_{\mathcal{T}} \nabla f \cdot \nabla g \, \mathrm{d}\lambda_{\mathcal{T}}, \ \mathcal{D}(\mathcal{E}) = \{ f \in L^2(\nu) \cap \mathcal{C}_{\infty} \mid \nabla f \in L^2(\lambda_{\mathcal{T}}) \}$$

Lemma (∇ , [Athreya, L., WINTER '14⁺: Invariance...])

If $f: T \to \mathbb{R}$ is absolutely continuous, then there exists a unique (up to λ_T -zero sets) gradient $\nabla f \in L^1_{loc}(\lambda_T)$ with

$$f(x) - f(\rho) = \int_{[\rho, x]} \nabla f \, \mathrm{d}\lambda_T \qquad \forall x \in T$$

- ∇ depends on ρ , even for \mathbb{R} -trees, where λ_T does not
- $T = \mathbb{R}_+$, $\rho = 0$: ∇ is the usual gradient on \mathbb{R}
- $T = \mathbb{R}$, $\rho = 0$: $\nabla f(x) = \operatorname{sgn}(x)f'(x) = \pm f'(x)$
- finite tree: $\nabla f(x) = f(x) f(y)$ where (x, y) is the unique edge towards ρ , i.e. with $y \in [\rho, x]$

The Dirichlet form: speed- ν motion

$\mathcal{E}(f,g) = \frac{1}{2} \int_{\mathcal{T}} \nabla f \cdot \nabla g \, \mathrm{d}\lambda_{\mathcal{T}}, \ \mathcal{D}(\mathcal{E}) = \{ f \in L^2(\nu) \cap \mathcal{C}_{\infty} \mid \nabla f \in L^2(\lambda_{\mathcal{T}}) \}$

Fact [FUKUSHIMA, OSHIMA, TAKEDA '94]: To a regular Dirichlet form on $L^2(\nu)$ corresponds a ν -symmetric Markov process with generator G characterised by $\mathcal{E}(f,g) = \langle Gf,g \rangle_{\nu}$

Proposition ([ATHREYA, L., WINTER '14⁺: *Invariance...*])

 $(\mathcal{E}, \mathcal{D}(\mathcal{E}))$ is closable and its closure is a regular Dirichlet form. The corresponding Markov process $X = (X_t)_{t \ge 0}$ is the speed- ν motion.

- Although λ_T and ∇ depend on ρ , the form $\mathcal E$ does not
- ${\mathcal E}$ need not be *conservative*, i.e. X may hit ∞ in finite time
- X has continuous paths iff (T, r) is an \mathbb{R} -tree, i.e. connected
- Jumps occur precisely over edges
- $T = \mathbb{R}$, $\nu = \lambda_{\mathbb{R}}$: X is standard Brownian motion
- $T = \mathbb{R}$, ν arbitrary: X is process considered in [Stone '63]

The Dirichlet form: speed- ν motion

$$\mathcal{E}(f,g) = \frac{1}{2} \int_{\mathcal{T}} \nabla f \cdot \nabla g \, \mathrm{d}\lambda_{\mathcal{T}}, \ \mathcal{D}(\mathcal{E}) = \{ f \in L^2(\nu) \cap \mathcal{C}_{\infty} \mid \nabla f \in L^2(\lambda_{\mathcal{T}}) \}$$

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(T, r) R-tree: X is the ν-BM [ATHREYA, ECKHOFF, WINTER '13]
(T, r) finite tree: X jumps from x to y ~ x with rate

$$\gamma_{x,y} = (2\nu(\{x\})r(x,y))^{-1}$$

• (T, r) finite tree with unit edge-lengths: $r_{x,y} = 1$ for $x \sim y$. ν counting measure \rightsquigarrow degree-dependent total jump rate

$$\gamma_x = \sum_{y \sim x} \gamma_{x,y} = \frac{1}{2} \deg(x)$$

We get the constant speed (simple) RW with

$$\nu(\{x\}) = \frac{1}{2} \deg(x)$$

Convergence of mm-trees

 $x_n = (T_n, r_n, \rho_n, \nu_n), \ x = (T, r, \rho, \nu)$ are mm-trees. Recall $T_n = \text{supp}(\nu_n)$

Definition (Gromov-vague & Gromov-Hausdorff-vague topology)

 $x_n \xrightarrow{\text{Gv}} x$ (**Gromov-vague** convergence) if $(T_n, r_n), (T, r)$ can be isometrically embedded in a metric space (E, d) such that, in this embedding, $\rho_n \to \rho$ and for balls $B = B_R(\rho)$ of radius R in (E, d)

$$u_n \upharpoonright_B \xrightarrow[n \to \infty]{w} \nu \upharpoonright_B \quad \text{for almost all } R > 0$$

- *Gv-topology* is a simple modification of *Gromov-weak topology* (finite measures) [GREVEN, PFAFFELHUBER, WINTER '09]
- Gromov's □₁-metric [GROMOV '99: Metric structures...] induces the Gw-topology, shown in [L. '13: Equivalence of Gromov-Prohorov...]

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 $\chi_n \xrightarrow{\text{Gv}} \chi$ (**Gromov-vague** convergence) if $(T_n, r_n), (T, r)$ can be isometrically embedded in a metric space (E, d) such that, in this embedding, $\rho_n \to \rho$ and for balls $B = B_R(\rho)$ of radius R in (E, d)

$$u_n \upharpoonright_B \xrightarrow[n \to \infty]{w} \nu \upharpoonright_B \quad \text{for almost all } R > 0$$

 $\begin{array}{c} \chi_n \xrightarrow{\text{GHv}} \chi \text{ (Gromov-Hausdorff-vague convergence) if additionally} \\ T_n \cap B \xrightarrow{\text{Hausdorff}} T \cap B \quad \text{ for almost all } R > 0 \end{array}$

- GHv-topology closely related to Gromov-Hausdorff-Prohorov metric but subtle difference: full-support assumption / equivalence classes
- → The GHP-metric is *not complete* on spaces of spaces with full support

The gap between Gv and GHv topologies

Proposition ([ATHREYA, L., WINTER '14⁺: The gap between...])

• The GHv-topology is Polish, the Gv-topology is Lusin

• The Gv-topology *not* Polish. It becomes Polish if we drop the *Heine-Borel* assumption

The gap between Gv and GHv topologies

Proposition ([ATHREYA, L., WINTER '14⁺: *The gap between...*])

The GHv-topology is Polish, the Gv-topology is Lusin

•
$$x_n \xrightarrow{\text{GHv}} x$$
 if and only if $x_n \xrightarrow{\text{Gv}} x$ and the lower mass-bound

$$\liminf_{n\to\infty}\inf_{x\in B_R(\rho_n)}\nu_n(B_{\delta}(x))>0\qquad \forall R>0\qquad (3)$$

In this case, (E, d) can be chosen as Heine-Borel space.

Gv-topology is induced by the algebra of functions of the form

$$\Phi(x) = \int_{\mathcal{T}^m} \varphi(r(x_i, x_j)_{i,j=0,\dots,m}) \nu^{\otimes m}(\mathrm{d} x), \quad x_0 := \rho,$$

for $m \in \mathbb{N}, \ \varphi \in \mathcal{C}_{c}(\mathbb{R}^{(m+1) \times (m+1)}).$ Can use Le Cam:

→ For random variables: $\mathcal{X}_n \xrightarrow[G_v]{\mathcal{L}} \mathcal{X} \Leftrightarrow \mathbb{E}[\Phi(\mathcal{X}_n)] \to \mathbb{E}[\Phi(\mathcal{X})] \forall \Phi$ • (3) acts as a *tightness condition* We use the same *embedding approach* as for the definition of Gvand GHV-topology to define convergence of *processes living on different spaces*:

Definition (convergence of processes on different spaces)

Let $X^n = (X_t^n)_{t \ge 0}$, $n \in \mathbb{N} \cup \{\infty\}$, be stochastic processes with values in (T_n, r_n) . We say that X^n converges to $X = X^\infty$ in pathspace or f.d.d. if (T_n, r_n) can be *isometrically embedded* in a *metric space* (E, d) such that, in this embedding, X^n converges to X in pathspace or f.d.d., respectively, as E-valued processes.

The Result

 $x_n = (T_n, r_n, \rho_n, \nu_n); X^n$ is the speed- ν_n motion on (T_n, r_n) started in ρ_n

Theorem ([Athreya, L., Winter '14⁺: Invariance principle...])

Assume X is conservative, and consider the conditions (R > 0)

- Edge-length bound: $\limsup_{n \to \infty} \sup \{ r_n(x, y) \mid r_n(\rho_n, x) < R, (x, y) \text{ edge} \} < \infty$
- **2** Gromov-vague convergence: $x_n \xrightarrow{Gv} x$
- 3 Lower mass-bound: $\liminf_{n\to\infty} \inf_{x\in B_R(\rho_n)} \nu_n(B_{\delta}(x)) > 0$
- Diameter bound: $\sup_n \operatorname{diam}(T_n, r_n) < \infty$
- If (1), (2) and (3) hold, then X^n converges in pathspace to X. If (1), (2) and (3) hold, then X^n converges f.d.d. to X.
- is a weak condition; trivially satisfied for R-trees (no edges)
 can be weakened, but some condition is needed

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Consider the conditions (R > 0)

• Edge-length bound: $\limsup_{n \to \infty} \sup \{ r_n(x, y) \mid r_n(\rho_n, x) < R, (x, y) \text{ edge} \} < \infty$

2 Gromov-vague convergence: $\chi_n \xrightarrow{G_v} \chi$

3 Lower mass-bound: $\liminf_{n\to\infty} \inf_{x\in B_R(\rho_n)} \nu_n(B_{\delta}(x)) > 0$

If (1), (2) and (3) hold, then X^n converges in pathspace to a process Y on the one-point compactification of T, and Y killed at infinity coincides with X

- Speed ν -motions are always killed at infinity
- The limit process Y may hit ∞ and not stay there
 - $\rightsquigarrow Y$ looses the Markov property at ∞ and defines entrance laws for X from ∞

For pathspace convergence (under the lower mass-bound):

- **1** Tightness using the Aldous criterion
- Strong Markov property of all limit processes (compact case)
 - show equicontinuity of the maps P_n: (t, x) → L_x(Xⁿ_t), n ∈ N, where L_x is the law of a process started in x; use Arzelà-Ascoli
- Show occupation time formula for all limit processes
 - \rightsquigarrow All *limit processes coincide* with X in the compact case
- approximate non-compact trees with compact trees

For pathspace convergence (under the lower mass-bound):

- **1** Tightness using the Aldous criterion
- Strong Markov property of all limit processes (compact case)
 - show equicontinuity of the maps P_n: (t, x) → L_x(Xⁿ_t), n ∈ N, where L_x is the law of a process started in x; use Arzelà-Ascoli
- Show occupation time formula for all limit processes
 - \rightsquigarrow All *limit processes coincide* with X in the compact case
- approximate non-compact trees with compact trees

For the f.d.d.-case (without the lower mass-bound):

- $\ \, \widehat{\mathsf{T}}_{n} \subseteq \mathsf{T}_{n}: \ \nu_{n}(\mathsf{T}_{n} \setminus \widehat{\mathsf{T}}_{n}) < \varepsilon, \ (\widehat{\mathsf{T}}_{n}, \mathsf{r}_{n}, \nu_{n}) \ \text{satisfies mass-bound}$
- Show closeness of marginals of X^n and \hat{X}^n
 - Use a simple *heat-kernel bound* satisfied for speed- ν motions X:

$$\left\|q_t(x,\cdot)\right\|_2^2 \leq \nu(T)^{-1} + \operatorname{diam}(T) \cdot t^{-1} \qquad \forall x \in T, \ t > 0$$

• Use *pathspace convergence* of \hat{X}^n and Markov property

Thank you for your attention!

Arigatō gozaimasu!