

Annealed Brownian motion in a heavy tailed Poissonian potential

Ryoki Fukushima

Research Institute of Mathematical Sciences

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Introduction

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$$u(t, x) = E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\}, B_t = x \right]$$

→ localization of the diffusion particle

1. Setting

- $(\{B_t\}_{t \geq 0}, P_x)$: $\kappa\Delta$ -Brownian motion on \mathbb{R}^d
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Potential

For a non-negative and integrable function v ,

$$V_\omega(x) := \sum_i v(x - \omega_i).$$

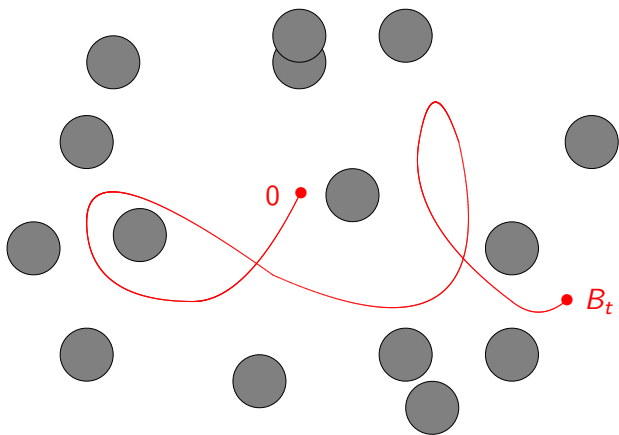
(Typically $v(x) = 1_{B(0,1)}(x)$ or $|x|^{-\alpha} \wedge 1$ with $\alpha > d$.)

Annealed measure

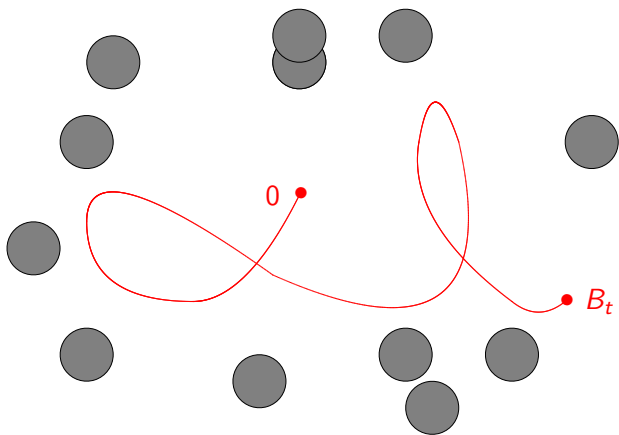
We are interested in the behavior of Brownian motion under the measure

$$Q_t(\cdot) = \frac{\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \mathbb{P} \otimes P_0(\cdot)}{\mathbb{E} \otimes E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \right]}.$$

The configuration is not fixed and hence Brownian motion and ω_i 's tend to avoid each other.



$\exp\{-\int_0^t V_\omega(B_s)ds\}$: large, \mathbb{P} : large, P_0 : small



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2. Light tailed case

Donsker and Varadhan (1975)

When $v(x) = o(|x|^{-d-2})$ as $|x| \rightarrow \infty$,

$$\mathbb{E} \otimes E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \right] = \exp \left\{ -c(d, \kappa) t^{\frac{d}{d+2}} (1 + o(1)) \right\}$$

as $t \rightarrow \infty$.

Remark

$$c(d, \kappa) = \inf_U \{ \kappa \lambda^D(U) + |U| \}.$$

Suppose v is compactly supported for simplicity. Then

$$\begin{aligned} \mathbb{E} \otimes E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \right] \\ \geq P_0 (B_{[0,t]} \subset U) \mathbb{P}(\omega(U) = 0) \\ \approx \exp\{-\kappa \lambda^D(U)t - |U|\}. \end{aligned}$$

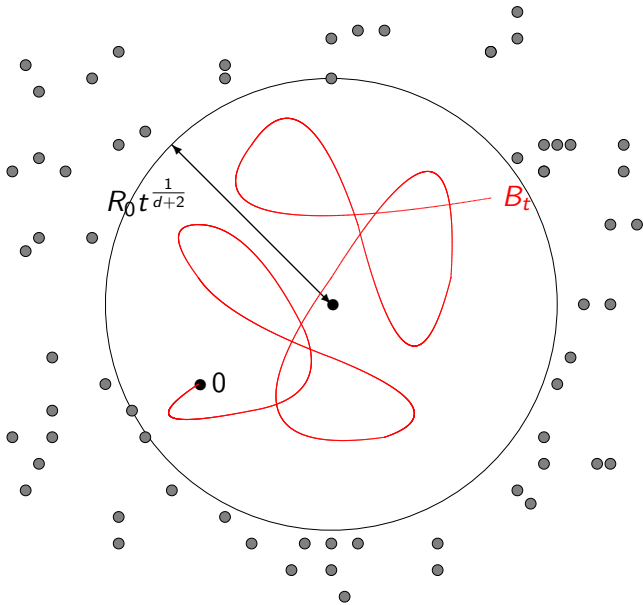
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Optimizing over U , we get the correct lower bound.

$$\text{maximizer} = B(x, t^{\frac{1}{d+2}} R_0)$$



One specific strategy gives dominant contribution to the partition function.



It occurs with high probability under the annealed path measure.

Sznitman (1991, $d = 2$) and Povel (1999, $d \geq 3$)

When ν has a compact support, there exists

$$D_t(\omega) \in B\left(0, t^{\frac{1}{d+2}}(R_0 + o(1))\right)$$

such that

$$Q_t \left(B_{[0,t]} \subset B\left(D_t(\omega), t^{\frac{1}{d+2}}(R_0 + o(1))\right) \right) \xrightarrow{t \rightarrow \infty} 1.$$

Remark

Bolthausen (1994) proved the corresponding result for two-dimensional random walk model.

3. Heavy tailed case

Pastur (1977)

When $v(x) \sim |x|^{-\alpha}$ ($\alpha \in (d, d + 2)$) as $|x| \rightarrow \infty$,

$$\mathbb{E} \otimes E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \right] = \exp \left\{ - a_1 t^{\frac{d}{\alpha}} (1 + o(1)) \right\},$$

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Unfortunately, this first order asymptotics tells us little about the Brownian motion.

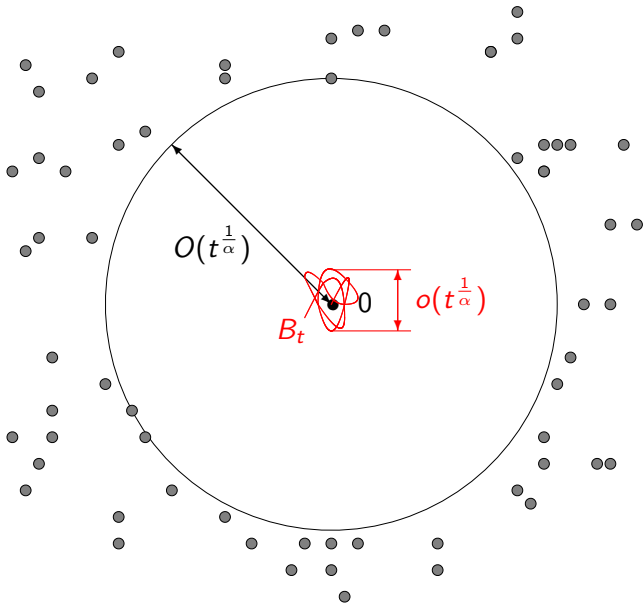
In fact, Pastur's proof goes as follows:

$$\begin{aligned}\mathbb{E} \otimes E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \right] \\ \approx \mathbb{E}[\exp\{-tV_\omega(0)\}] \\ \sim \exp\{-a_1 t^{\frac{d}{\alpha}}\}.\end{aligned}$$

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The effort of the Brownian motion is hidden in the higher order terms. A bit more careful inspection of the proof shows...



F. (2011)

When $v(x) = |x|^{-\alpha} \wedge 1$ ($d < \alpha < d + 2$),

$$\begin{aligned} \mathbb{E} \otimes E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \right] \\ = \exp \left\{ -a_1 t^{\frac{d}{\alpha}} - (a_2 + o(1)) t^{\frac{\alpha+d-2}{2\alpha}} \right\}, \end{aligned}$$

where

$$a_2 := \inf_{\|\phi\|_2=1} \left\{ \int \kappa |\nabla \phi(x)|^2 + C(d, \alpha) |x|^2 \phi(x)^2 dx \right\}.$$

Remark

The proof is an application of the general machinery developed by Gärtner-König 2000.

Recalling the Donsker-Varadhan LDP

$$P_0 \left(\frac{1}{t} \int_0^t \delta_{B_s} ds \sim \phi^2(x) dx \right) \approx \exp \left\{ -t \int \kappa |\nabla \phi(x)|^2 dx \right\},$$

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In particular, since $P_0 (B_{[0,t]} \subset B(x, R)) \approx \exp\{-tR^{-2}\}$, the localization scale should be

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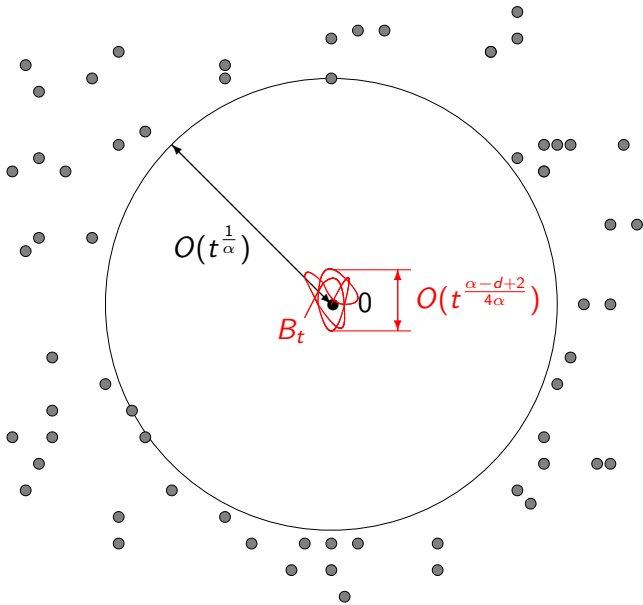
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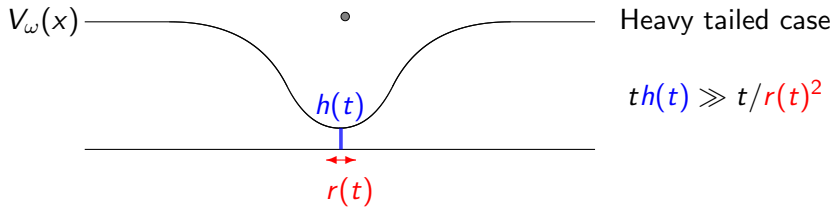
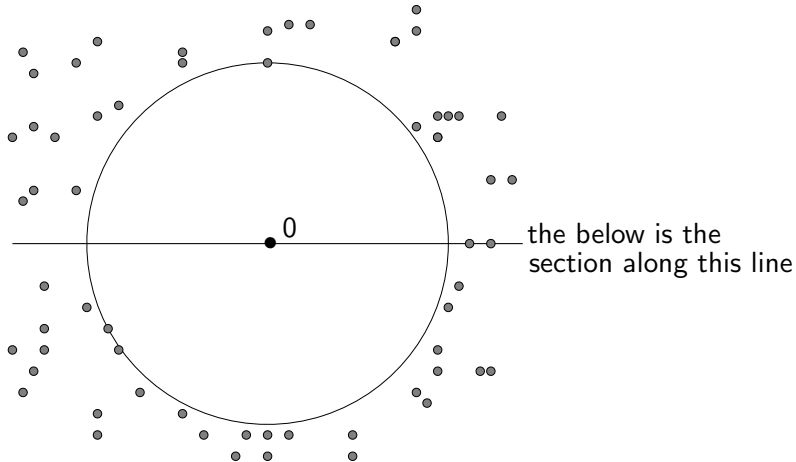
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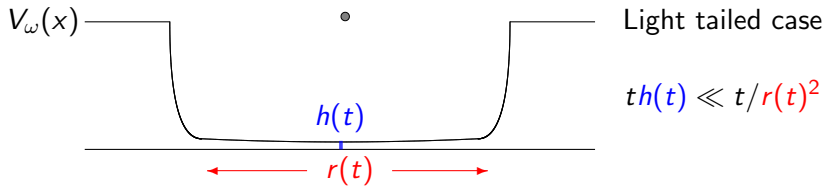
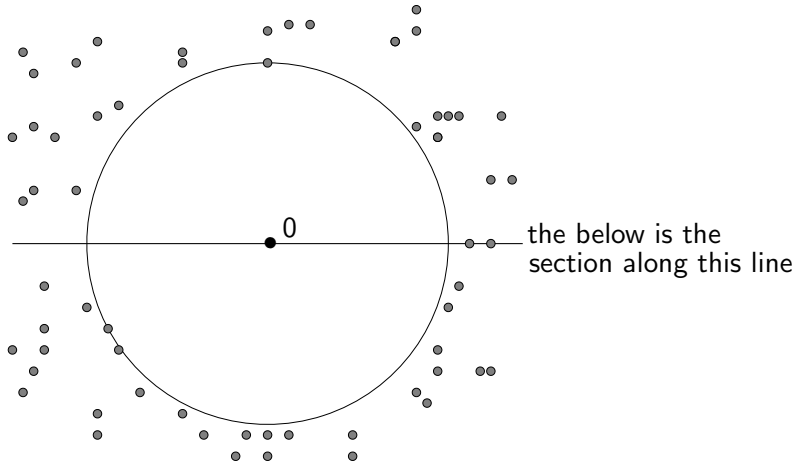
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In addition, the term $\int C(d, \alpha) |x|^2 \phi(x)^2 dx$ says that V_ω (locally) looks like a parabola.







Main Theorem (F. 2012)

$$Q_t \left(B_{[0,t]} \subset B \left(0, t^{\frac{\alpha-d+2}{4\alpha}} (\log t)^{\frac{1}{2}+\epsilon} \right) \right) \xrightarrow{t \rightarrow \infty} 1,$$

$$Q_t \left(V_\omega(x) - V_\omega(m_t(\omega)) \sim t^{-\frac{\alpha-d+2}{\alpha}} C(d, \alpha) |x - m_t(\omega)|^2 \right. \\ \left. \text{in } B(0, t^{\frac{\alpha-d+2}{4\alpha} + \epsilon}) \right) \xrightarrow{t \rightarrow \infty} 1,$$

$$\left\{ t^{-\frac{\alpha-d+2}{4\alpha}} B_{t^{\frac{\alpha-d+2}{2\alpha}} s} \right\}_{s \geq 0} \xrightarrow{\text{in law}} \text{OU-process with} \\ \text{“random center”,}$$

where $m_t(\omega)$ is the minimizer of V_ω in $B(0, t^{\frac{\alpha-d+2}{4\alpha}} \log t)$.

4. Outline of the proof

An important feature of this model is that there are two scales in the “optimal strategy”.

- ▶ ω lives in the scale $t^{1/\alpha}$,
- ▶ $\{B_s\}_{s \leq t}$ lives in the scale $o(t^{1/\alpha})$.

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This, for instance, prevents us from using the “compactification by projecting on a torus”.

But on the other hand, this helps us since it allows us to treat ω and B_s “separately”.

Suppose we have a crude estimate

$$\sup_{0 \leq s \leq t} |B_s| = o(t^{1/\alpha}).$$

Then $B_s \approx 0$ viewed from ω . Thus it is plausible that

$$Q_t(d\omega) \sim \frac{\mathbb{E}[\exp\{-tV_\omega(0)\} : d\omega]}{\mathbb{E}[\exp\{-tV_\omega(0)\}]}.$$

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The right hand side is nothing but the Poisson point process with intensity $e^{-t(|x|^{-\alpha} \wedge 1)} dx$.

- potential locally looks like parabola,
- localization, weak convergence.

It remains to verify $\sup_{0 \leq s \leq t} |B_s| = o(t^{1/\alpha})$. This is a localization but weaker than the main theorem.

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No! What we need is crude control which can be established with bare hands.

In what follows, we assume V_ω takes its minimum value at 0 for simplicity.

4.1 Crude control on the potential

Lemma 1

$$Q_t \left(V_\omega(0) \in \frac{d}{\alpha} a_1 t^{-\frac{\alpha-d}{\alpha}} + t^{-\frac{3\alpha-3d+2}{4\alpha}} (-M_1, M_1) \right) \rightarrow 1.$$

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Idea

$$Z_t \approx \mathbb{E}[\exp\{-tV_\omega(0)\}] \begin{cases} = \exp\left\{-a_1 t^{\frac{d}{\alpha}}\right\}, \\ \approx \sup_{h>0} [e^{-th} \mathbb{P}(V_\omega(0) \approx h)]. \end{cases}$$

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$\frac{d}{\alpha} a_1 t^{-\frac{\alpha-d}{\alpha}} = h(t)$ is the maximizer.

$$\begin{aligned} \Rightarrow \mathbb{E} \otimes E_0 \left[\exp\left\{-\int_0^t V_\omega(B_s) ds\right\} : V_\omega(0) \text{ is far from } h(t) \right] \\ \leq \mathbb{E}[\exp\{-tV_\omega(0)\} : V_\omega(0) \text{ is far from } h(t)] = o(Z_t). \end{aligned}$$

Lemma 2

$$Q_t \left(V_\omega(0) + V_\omega(x) \geq 2h(t) + c_1 t^{-\frac{\alpha-d+2}{\alpha}} |x|^2 \right. \\ \left. \text{for } t^{\frac{\alpha-d+6}{8\alpha}} < |x| < M_2 t^{\frac{\alpha-d+6}{8\alpha}} \right) \rightarrow 1.$$

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By Lemma 1,

$$\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \lesssim \exp \{ -th(t) \} = \exp \left\{ -\frac{d}{\alpha} a_1 t^{\frac{d}{\alpha}} \right\}$$

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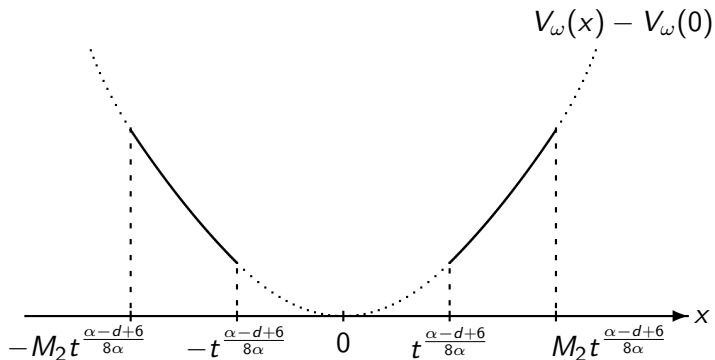
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Then, use

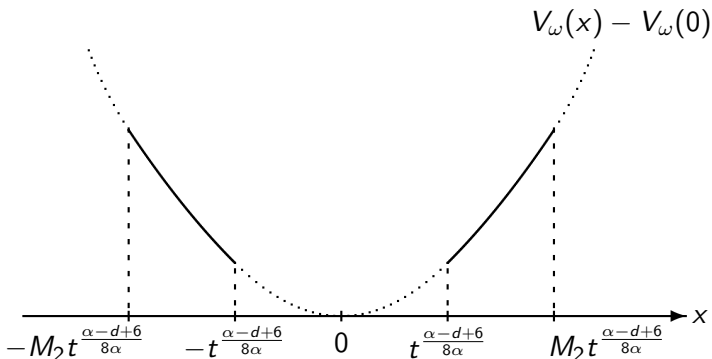
$$\mathbb{E} \left[\exp \left\{ -\frac{t}{2} (V_\omega(0) + V_\omega(x)) \right\} \right] \approx \exp \left\{ -a_1 t^{\frac{d}{\alpha}} - c_2 t^{\frac{d-2}{\alpha}} |x|^2 \right\}$$

and Chebyshev's inequality.

4.2 Crude control on the trajectory



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By “penalizing a crossing”,

$$Q_t \left(B_{[0,t]} \subset B \left(0, M_2 t \frac{\alpha-d+6}{8\alpha} \right) \right) \rightarrow 1.$$

How about the critical case $\alpha = d + 2$?

Ôkura (1981) proved

$$\mathbb{E} \otimes E_0 \left[\exp \left\{ - \int_0^t V_\omega(B_s) ds \right\} \right] = \exp \left\{ - \tilde{c}(d, \kappa) t^{\frac{d}{d+2}} (1 + o(1)) \right\}$$

as $t \rightarrow \infty$, where

$$\tilde{c}(d, \kappa) = \inf_{\|\phi\|_2=1} \left\{ \int \kappa |\nabla \phi(x)|^2 + 1 - \exp \left\{ - \int \frac{\phi(y)^2}{|x-y|^{d+2}} dy \right\} dx \right\}.$$

Thank you!

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